# The compactified configuration space and regularity for conical metrics

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Configuration of conical metrics

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## Outline



Constant curvature conical metrics

2 Compactification of configuration family





Motivation and further application

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#### Constant curvature metric with conical singularities

Consider a compact Riemann surface M, with the following data:

- *k* distinct points  $\mathfrak{p} = (p_1, \ldots, p_k)$
- Angle data  $\vec{\beta} = (\beta_1, \dots, \beta_k) \in (0, \infty)^k$
- Curvature constant  $K \in \{-1, 0, 1\}$
- Area A
- Conformal structure c given by M

A constant curvature metric with prescribed conical singularities is a smooth metric with constant curvature, except near  $p_j$  the metric is asymptotic to a cone with angle  $2\pi\beta_j$ .

(Gauss–Bonnet) 
$$\chi(M, \vec{eta}) := \chi(M) + \sum_{j=1}^{k} (\beta_j - 1) = \frac{1}{2\pi} KA$$

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#### Local structure near a cone point

Locally near a cone point with angle  $2\pi\beta$ , there are coordinates (geodesic polar coordinates) such that the metric is given by

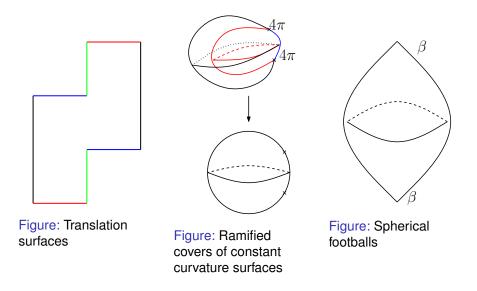
$$g = \begin{cases} dr^2 + \beta^2 r^2 d\theta^2 & K = 0; \\ dr^2 + \beta^2 \sin^2 r d\theta^2 & K = 1; \\ dr^2 + \beta^2 \sinh^2 r d\theta^2 & K = -1 \end{cases}$$

In the flat case, relating to the conformal structure

$$r = \frac{1}{\beta} |z|^{\beta}$$
, then  $g = |z|^{2(\beta-1)} (d|z|^2 + |z|^2 d\theta^2) = |z|^{2(\beta-1)} |dz|^2$ 

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## Some examples of constant curvature conical metrics



## **Existence and Uniqueness**

#### Theorem (88' McOwen, 91' Troyanov, 92' Luo-Tian)

For any compact surface M and conical data  $(\mathfrak{p}, \vec{\beta})$  satisfying one of the following constraints:

• 
$$\chi(M, \vec{\beta}) \leq 0; or$$
  
•  $\chi(M, \vec{\beta}) > 0, \vec{\beta} \in (0, 1)^k$   
•  $k = 2, \beta_1 = \beta_2; or$   
•  $k \geq 3, \beta_j + k - \chi(M) > \sum_{i \neq j} \beta_i, \forall j.$ 

there is a unique constant curvature metric with the prescribed singularities.

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## The moduli space for $\vec{\beta} \in (0, 1)^k$

#### Theorem (Mazzeo–Weiss, 2015)

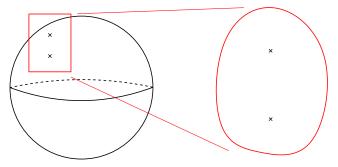
- The spaces of constant curvature conical metrics  $\mathcal{CM}_{cc}(M,\mathfrak{p})$  are Banach manifolds.
- There is an embedded (6γ − 6 + 3k)-dimensional submanifold S ⊂ CM<sub>cc</sub>(M, p) which is the quotient by the action of diffeomorphism group, i.e. the moduli space.

#### Question

- What happens when cone points collide?
- Ompactification of the moduli space?

#### When two points collide

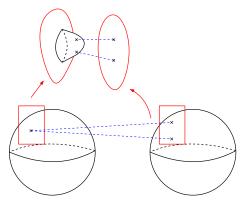
Scale back the distance between two cone points ("blow up")



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#### When two points collide

- Scale back the distance between two cone points ("blow up")
- Half sphere at the collision point, with two cone points over the half sphere:

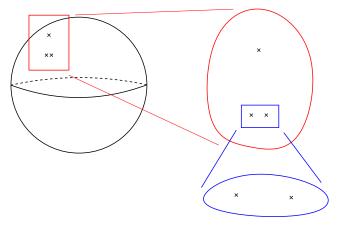


• Flat metric on the half sphere, and curvature *K* metric on the original surface

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#### Iterative structure





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#### Iterative structure

- "bubble over bubble" structure
- Higher codimensional faces from deeper scaling
- Flat conical metrics on all the new faces

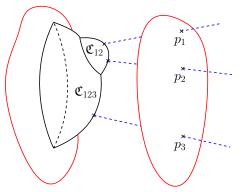


Figure: One of the singular fibers in  $\mathcal{C}_3$ , where two of the points collide faster than the third one

## Resolution of the configuration space

This "bubbling" process can be expressed in terms of blow-up of product  $M^k \times M \to M^k$ 

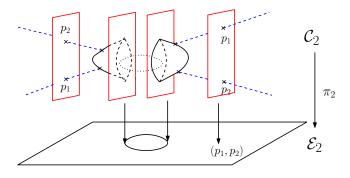


Figure: "Centered" projection of  $\mathcal{C}_2 \to \mathcal{E}_2$ 

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## When there are more cone points

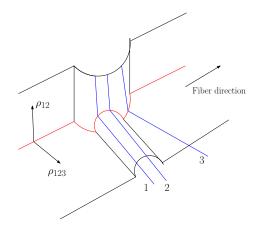


Figure: A schematic picture of resolved total space: cone points are marked blue, they become "separated" on the new faces; the most singular fiber is marked by red

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Results about fiber metrics on  $C_k$ 

#### Theorem (Mazzeo–Z, 2017)

For any<sup>\*</sup> given  $\vec{\beta}$ , the family of constant curvature metrics with conic singularities is polyhomogeneous on  $C_k$ .

- \*The metric family can be hyperbolic / flat (with any cone angles), or spherical (with angles less than 2π, except footballs)
- Start by constructing a model metric *g*<sub>0</sub>, then solve the curvature equation uniformly

$$\Delta_{g_0}u - Ke^{2u} + K_{g_0} = 0$$

• When K = 0, the curvature equation is linear

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## The flat case

#### Theorem (Flat case)

The fiber flat conical metrics with fixed cone angles  $\vec{\beta}$  and varying cone points  $\mathfrak{p}$  lift to be polyhomogeneous on  $C_k$ .

- The conformal factor is the sum of Green's functions
- Prove regularity by direct computation
- The metric on the front face is a rescaled conical metric with scattering (Euclidean) boundary
- Induction on the depth of the corner

#### Proof sketch for nonflat case

1) Construct an approximate solution, which involves iteratively solving equations on faces with increasing depth

$$\Delta_{g_0} u_N - K e^{2u_N} + K_{g_0} = \mathcal{O}(\rho^N)$$

2) Implicit function theorem to obtain the actual solution

$$\Delta_{g_0}(u_N + v_N) - K e^{2(u_N + v_N)} + K_{g_0} = 0$$

- 3) Commutator argument to show the regularity of  $v_N$  near the boundary faces
- 4) Together with the arbitrarily high order expansion, we obtain polyhomogeneity of  $u = u_N + v_N$

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## Consequences of the theorem

#### Theorem

For fixed angles  $\vec{\beta}$ , the fiberwise hyperbolic (resp. spherical) conical metrics are polyhomogeneous on  $C_k$ .

- The leading term of the metric is given by the flat metric
- When  $K = \pm 1$ , the difference from the flat metric is bounded by  $O(\rho^{\epsilon})$
- This matches the blow up limit

Motivation: positive curvature with big cone angles

- Literature: [Troyanov, 1991] [Umehara–Yamada, 2000] [Eremenko, 2000] [Eremenko–Gabrielov–Tarasov, 2014] [Eremenko–Gabrielov, 2015] [Bartolucci–De Marchis–Malchiodi, 2011] [Carlotto–Malchiodi, 2012] [Malchiodi, 2016]
- [Mondello–Panov, 2016]: spherical conical metrics on S<sup>2</sup> under the angle "holonomy condition"

$$d_{\ell^1}(ec{eta}-ec{1},\mathbb{Z}_{\mathit{odd}}^k)\geq 1$$

• When the above equality holds: [Dey, 2017] [Kapovich, 2017] [Eremenko, 2017]

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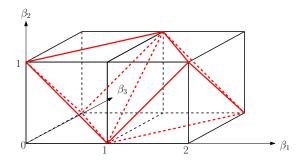


Figure: The admissible region for angle  $(\beta_1, \beta_2, \beta_3)$ : interior of the tetrahedra, extended by reflection symmetry

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#### Questions to answer

#### Goal: Find out the structure of the moduli space

- The full solution space: for given admissible (β
   , p, c), how many solutions are there?
- Deformation theory: is there a manifold structure?

## Invertibility of the linearized operator $\Delta_g - 2K$

- The linearized operator for the nonlinear curvature equation is given by  $\Delta_g 2K$
- The Friedrichs extension of the Laplacian ∆<sub>g</sub> is self-adjoint and has discrete spectrum
- When K < 0,  $\Delta_g 2K$  is invertible; K = 0, only kernel is the constant
- When K > 0 and β ∈ (0, 1)<sup>k</sup>, the first nonzero eigenvalue of Δ<sub>g</sub> satisfies λ<sub>1</sub> ≥ 2K, and equality is only achieved by the footballs
- This argument only works for all  $\beta_i < 1$
- Eigenfunctions become too singular when cone angle increases, so the Lichnerowicz type argument would not work

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## Eigenvalue 2: obstruction of operator invertibility

- Intuition: when angles increase, eigenvalues of the Laplacian decrease
- Example: two footballs glued together

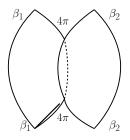


Figure: A surface with six conical points, with eigenvalue 2

• Expect stratum with eigenvalue 2 to appear in the interior, and extend to infinity.

#### Indicial roots

- The indicial roots of the flat conical Laplacian  $r^{-2} ((r\partial_r)^2 + \beta^{-2}\partial_{\theta}^2)$
- For k-th mode, the indicial root given by

$$\pm \frac{k}{\beta}$$
, with kernel  $r^{\pm \frac{k}{\beta}} e^{ik\theta}$ 

When Δ has eigenvalue 2, the kernel of Δ – 2 is prescribed by those indicial roots locally. When β > 1, these roots between (-1,0) are obstructions to surjectivity.

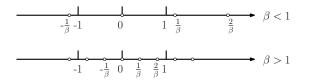


Figure: Indicial roots for different  $\beta$ 

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## Geometric realization of the indicial roots

We discover that one key step to make it unobstructed is the following:

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Proposition (Mazzeo–Z, in progress)
The linear space generated by the splitting of cone angles are
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spanned by  $\{r^{-\frac{k_i}{\beta}}, 1 \leq k_i < \beta\}.$ 

- Proof by computing the Jacobi field generated by the geometric motion
- The linearized operator is surjective after adding those parameters
- It provides additional coordinates for the moduli space

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Thank you for your attention!

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